

2017 Pepper range ses affaires - Task #8445

Feature # 8303 (Closed): Elaboration des Algorithmes

Task # 8325 (Closed): Utilisation des differents capteurs et actionneurs

Task # 8394 (Closed): commande base Pepper

tests erreur detection obstacle

04/06/2017 04:07 PM - Maeva Garcia

Status:	Closed	Start date:	04/05/2017
Priority:	Normal	Due date:	04/10/2017
Assignee:	Maeva Garcia	% Done:	100%
Category:		Estimated time:	8.00 hours
Target version:	Revue d'appel d'offre 2017		
Description			
realisation de tests pour voir si le robot se bloque ne veut plus avancer (obstacle detecté) alors qu'il n'y a pas d'obstacle. on a remplacer : roslaunch pepper_bring pepper_full.launch nao_ip:=<PEPPER_IP> par : roslaunch naoqi_driver naoqi_driver.launch nao_ip:=<PEPPER_IP>			

History

#1 - 04/10/2017 11:34 AM - Maeva Garcia

- Due date changed from 04/07/2017 to 04/10/2017

- % Done changed from 0 to 30

#2 - 04/10/2017 11:41 AM - Maeva Garcia

- % Done changed from 30 to 100

#3 - 04/10/2017 11:42 AM - Maeva Garcia

- Status changed from In Progress to Closed

#4 - 10/03/2017 02:55 PM - Maeva Garcia

- Status changed from Closed to Resolved

#5 - 10/06/2017 04:04 PM - Maeva Garcia

- Status changed from Resolved to Closed